



# **FHWA/MDOT/UMTRI Integrated Mobile Observations 2.0 (IMO)**

Federal Highway Administration

Gabe Guevara, P.E.

Michigan Department of Transportation

Steven J. Cook, P.E.

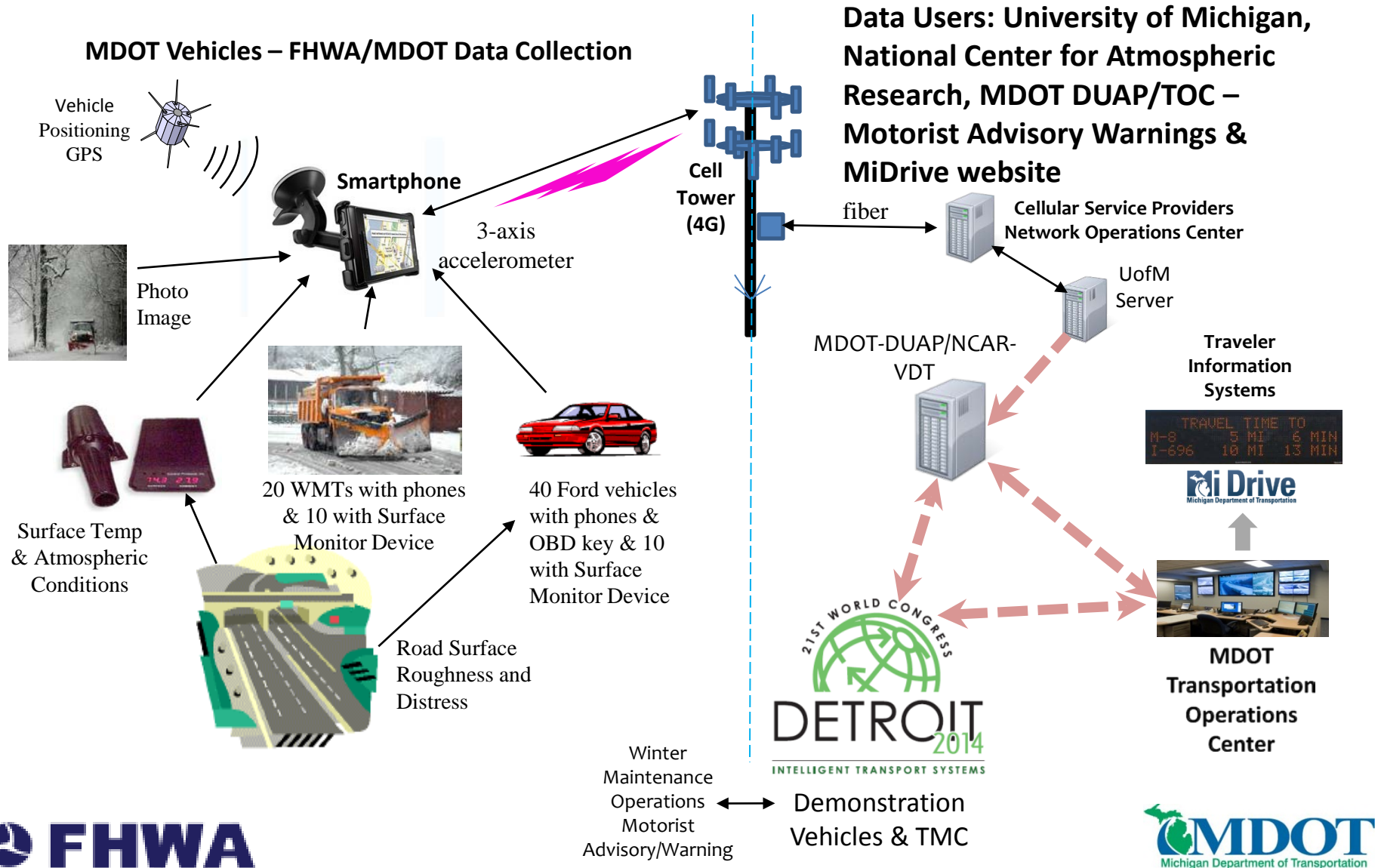
University of Michigan Transportation Research Institute

(UMTRI)

Bruce Belzowski

Cody Hyman

# FHWA/MDOT Integrated Mobile Observations (IMO) Architecture



# IMO Device Installations



# IMO DataProbe Data Sources

<u>SIGNAL</u>	<b>Droid</b>	<b>OBDKey</b>	<b>Surface Patrol</b>
Position	X		
Speed	X		
Direction	X		
Altitude	X		
Distance	X		
Vehicle dynamics	X		
Roughness	X		
Imaging	X		
VIN		X	
RPM		X	
Throttle Position		X	
ABS		X	
Traction Control		X	
Ambient Temp		X	
Barometer		X	
Air & Pavement Temp			X
Humidity			X
Dew Point			X

**Number of Vehicles:**      (60)      (40)      (20)



# Web Portal for Sending IMO Images

\*\*Photo also activated by ABS & traction control event or manually

**DATAPROBE FLEET COMMUNICATIONS**

Message to be sent:

Region	Location	Driver	Year	Model	Config	In Service	Req Photo	Send Message
SWS	SOUTH HAVEN GARAGE	Mark Grazioli	2006	F250	BC			
SWS	PLAINWEL GARAGE	Tom Simpson	2008	F250	BC	X	X	
SWS	COLOMA GARAGE	Hussain Ibrahim	2008	F250	BC			
SWS	KALAMAZOO GARAGE	Scott Geiger	2008	F250	BC			
SWS	COLOMA TSC	Keith Williams	2010	F250	BC	X	X	
SWS	COLOMA TSC	Ron Jackson	2009	SIERRA	BC	X	X	
SWS	JONES GARAGE	Rich Antuna	2009	SIERRA	BC			
SWS	FENNVILLE GARAGE	Mark Grazioli	2005	F250	BCS			
SWS	KALAMAZOO TSC	Tom Simpson	2006	F250	BCS			
SWS	JONES GARAGE	Hussain Ibrahim	2006	F250	BCS			
SWS	MARSHALL GARAGE	Scott Geiger	2006	F250	BC			
SWS	COLOMA TSC	Keith Williams	2006	F250	BC	X	X	
SWS	MARSHALL GARAGE	Ron Jackson	2008	Intern	BS	X		
SWS	REGION MAINTENANCE	Rich Antuna	2008	Intern	BS			

Vehicle fleet details  
maintained by  
administrator/operator

Identifies which  
vehicles are  
currently in-  
service

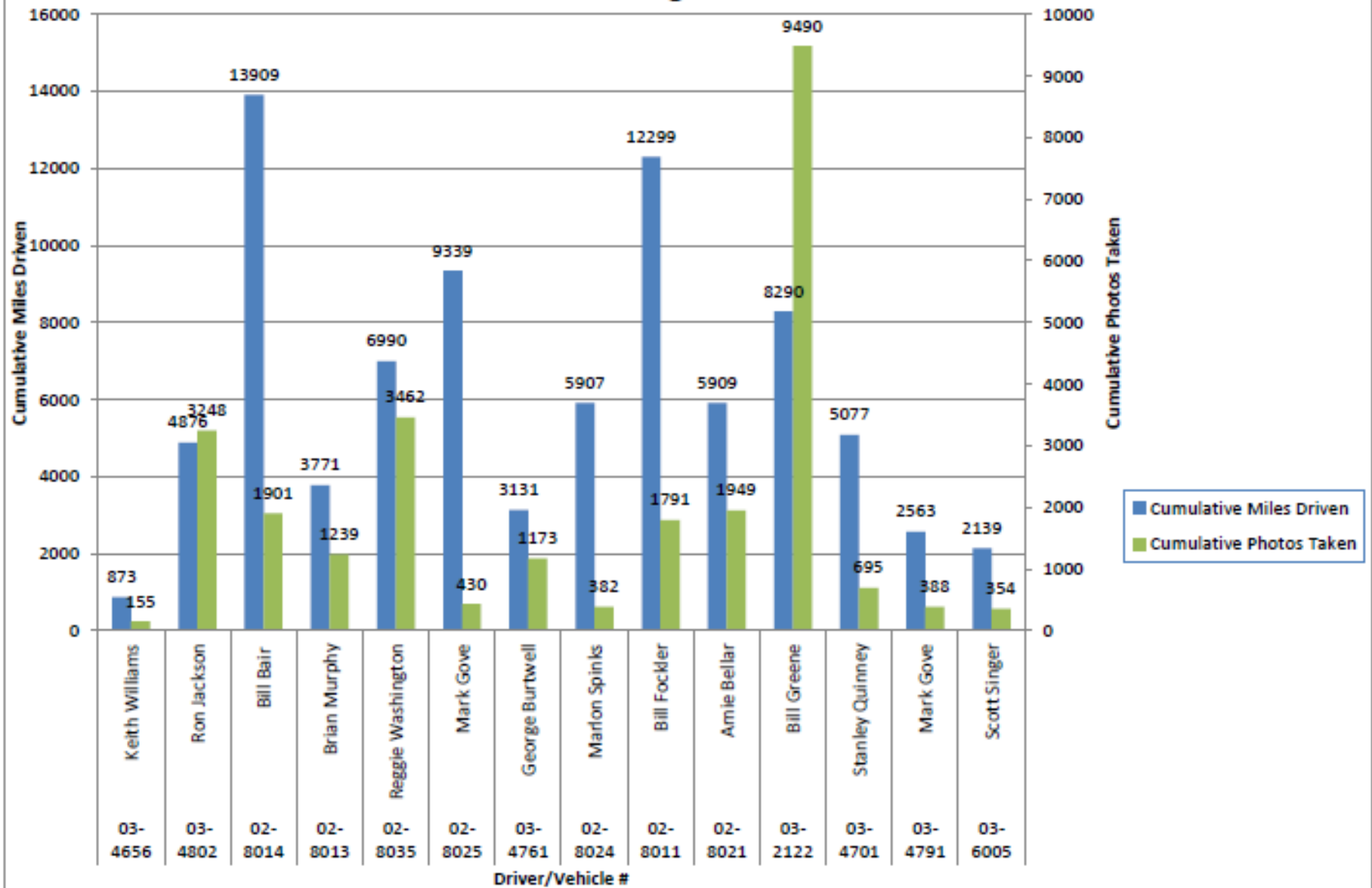
Operator selects  
images to be taken  
then clicks SEND

# Roadway Camera Images

- Images (jpg files) taken with the Droid camera
- Images triggered by ABS lockup & traction control event, web portal or manually
  - Three image sequence every two seconds
- Images sent to server in five minutes



## Cumulative Vehicle/Photo Inventory Metro Region FY2014



# IMO Final Report - Lessons Learned (first 17 months)

## Vehicles:

- Auto Maker(s) providing the necessary CAN data and technical support
- Tracking vehicles in service is difficult

## Hardware:

- Bluetooth serial adapter
- Phone charges can be significant: 60 phones (\$37/month/phone) \$2,220 per month
- Bluetooth link between the OBD key and DataProbe not consistent/reliable
- Wiring the phone power to the accessory fuse provided “key-on key-off” system

## Software:

- Remote phone software update & need internal staff to support development
- Remote software updates require testing and validation

## Communication:

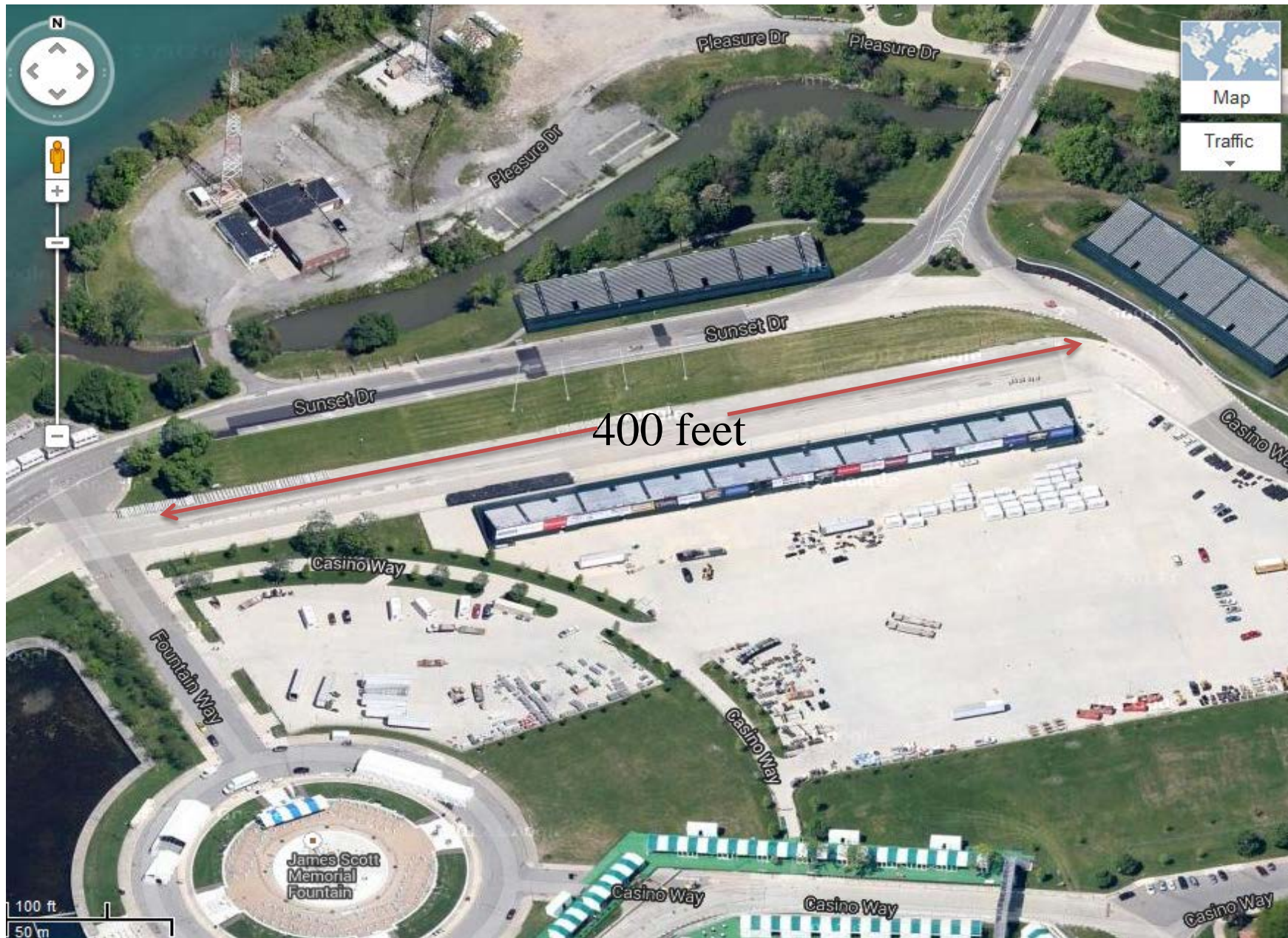
- Survey of drivers brought all the issues up front and helped prioritize work/issues/importance of project
- Comparing weekly miles driven/photos
- Weekly meetings with all stakeholders



# IMO Final Report - Conclusions (first 17 months)

- \*\*Delivered 196,204 valid data files to 6 weather analyst organizations throughout the U.S (~5 minute file/may include photos, 172 gigabytes)
- \*\*Drivers drove nearly 400,000 miles and took nearly 45,000 photos
- \*\*Collected all targeted data available on the sensors from vehicle
- Provided data quality check before sending (number of satellites, vehicles idling, etc.)
- Data timeliness: 5 minute to 1minute file uploads – UofM server QC for about 3 minutes (trying to reduce to less than one minute)
- Need more checking from server that data is within a valid range (QC)
- DataProbe system must become more reliable in its interactions with the OBD key and Surface Patrol
- \*\*Automakers technical support for CAN data
- Designed a web portal to take pictures and send message from the portal, and monitor the fleet of IMO vehicles in service (problems with vehicle staying linked to site)
- Need more information about vehicle/sensor functionality while in service
- \*\*Smartphone provides ubiquitous technology, affordable, widely used, etc.
- \*\*Technology provides micro level weather data use and processing
- \*\*Crowd sourcing opportunities with cell phone data collection
- \*\*More vehicles on the road(s) are necessary to reach the critical mass necessary for micro level weather data reporting (what is that critical mass?)
- The OpenXC [open source third party development (lead by Ford)]
- Analyzing photos may open another window for micro level weather reporting (automated process)

# IMO World Congress Demonstration - Belle Isle





# IMO Demo for WC - Two E350 Ford 10 Passenger Vans



Time  
10:19:57

GPS Location  
Lat: 42.33705°  
Long: -82.99703°  
Alt: 474.29ft

Velocity  
Speed: 10001<sub>mph</sub>  
Heading: 272.6°

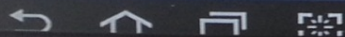
Roughness  
5.5

Engine  
Tach: - RPM  
Throttle: -%

Events  
Brakes ABS  
Wipers TCS  
ESP

Temperature  
Surface: -°F  
Air: -°F

Humidity/Dewpoint  
Humid: -%  
Dewpnt: -°F



INSIGNIA

10:29 AM 4G















# Contact Information

## FHWA/MDOT/UMTRI Final IMO Report

[www.michigan.gov/cv](http://www.michigan.gov/cv)

Steven J. Cook, P.E.  
Program Manager  
Michigan DOT  
[cooks9@michigan.gov](mailto:cooks9@michigan.gov)  
517-636-4094

Matt Pratt  
Michigan DOT  
[prattm@michigan.gov](mailto:prattm@michigan.gov)  
517-643-5372

Bruce Belzowski  
Co-Principal Investigator  
UMTRI  
[bbl@umich.edu](mailto:bbl@umich.edu)  
734-936-2704

Cody Hyman  
Co-Investigator  
UMTRI  
[hymanc@umich.edu](mailto:hymanc@umich.edu)  
734-936-2704

